Introduction to Microcontrollers

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What is a microcontroller??

 A Microcontroller is a VLSI (Very Large Scale Integration) Integrated Circuit (IC) that contains electronic computing unit and logic unit (combinedly known as CPU), Memory (Program Memory and Data Memory), I/O Ports (Input / Output Ports) and few other components integrated on a single chip.



What is a microcontroller??



 An embedded system relies on a combination of hardware and software implementation to fulfill a specific function that imposes time constrains.







 A Microprocessor is an Integrated Circuit (IC) that contains the Central Processing Unit (CPU).

Microprocessor



 A Microprocessor is an Integrated Circuit (IC) that contains the Central Processing Unit (CPU).

Block Diagram of Microprocessor

ALU	Reg	jisters
(Arithmetic Logic	Accur	mulator &
Unit)	Gener	al Purpose
Program Counter	Stack Pointer	Clock
(PC)	(SP)	Circuit
Interrupt Circuit		

Microprocessor



 It's a full computer system on a chip, even if its resources are far more limited than of a desktop personal computer. Microcontroller



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Block Diagram of Microprocessor





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Block Diagram of Microprocessor



Block Diagram of Microcontroller



 A System-on-Chip (SoC) is a silicon chip that contains one or more processor cores — microprocessors (MPUs) and/or microcontrollers (MCUs) and/or digital signal processors (DSPs) — along with on-chip memory, hardware accelerator functions, peripheral functions, and (potentially) all sorts of other "stuff."

System On Chip (SoC)



 ASIC (Application Specific Integrated Circuit) is a chip that is custom designed for a specific application. Usually designed by a company for a particular purpose or customer. This can be customized for a particular application, ensuring it meets the power and performance requirements of that specific application.



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• What is needed to start up a microcontroller?



- What is needed to start up a microcontroller?
- **Supply voltage**: depends on the microcontroller technology and is needed to power on the integrated electronics.



- What is needed to start up a microcontroller?
- Supply voltage
- **Pull up the reset pin**: It is needed to wake up the microcontroller from the reset state.



- What is needed to start up a microcontroller?
- Supply voltage
- Pull up the reset pin
- Microcontroller heartbeat: Microcontrollers and microprocessors depend on oscillators for basic timing and control. Oscillators are responsible for supplying the clock signals in microcontrollers. All the instructions executed by microcontrollers are in synchronization with clock signals.







- What is needed to start up a microcontroller?
- Supply voltage
- Pull up the reset pin
- Microcontroller heartbeat
- Where is the feature that allows **it to think**?





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Microcontroller memory

	Volatile Memory	Non-Volatile Memory
Description	Loses all the data when power is lost	Retains all the data when power cycled
Device uses	Cache, Registers, Static RAM (SRAM), Dynamic RAM (DRAM)	Hard disk drives, EEPROM, Flash memory
When is used	Temporary retention of data	Permanent retention of information



Microcontroller memory - Flash

- Also know as Program Memory
- Flash memory is widely used in embedded systems due to its numerous advantages, such as its ability to maintain data without power and quick access to stored data.

Oscillator 0 - 20MHz Internal Oscillator	SPI USART	T0 T1 T2 Timers CPU	SFR RAM (368) Program Memory 8K
A/D Converter Vref	CCP1, CCP2 PWM CCP/PWM modules	(35 instructions) Interrupts WDT	EEPROM (256) Memory
I/O Port Port A Por	t B Port C	Port D Port E	RESET Power Supply 2 - 5.5V

Pro	Const
High-density storage	Erasing data is limited to one sector at a time
Low cost	
Fast read time	Slower write times compared to RAM
Non-volatile, retaining data without power	
Electrically reprogrammable	Finite number of write/erase cycles

Microcontroller memory - RAM

- Also know as data memory
- Static Random Access Memory (SRAM) is a type of volatile memory used in embedded systems.



Pro	Const
Greater number of write/erase cycles compared to Flash	Higher cost-per-byte compared to DRAM and FLASH
Fast access times (very fast read/write speed)	Consumes more power than DRAM, and even more then FLASH
No refresh cycles required, unlike DRAM	Requires more transistors per memory cell, resulting in a larger chip size
Smallest write/read size (byte level)	

Microcontroller memory - EEPROM

 Electrically-Erasable-Programmable Read-Only Memory (EEPROM) is a hybrid memory device that combines features of both RAM and ROM (Read Only Memory).



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Pro	Const
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MSF-EXF450FR0909 Fin map	boosterPack standard	
- GND - P2.1 - (i) (TB0.5 DMAEO UCA0SOMI/RXD - P1.5 - (i) (TA0.0 SO UCA0CLK UCB0STE - P9.4 - ESICIO C12 A12 - P1.5 - (I) CE0SINO - (I) CE0SIDA - (TA0 1)	GND PWM out GPIO (!) SPI CS wireless GPIO (!) CPIO** RST MOSI	
P1.7 UCBOSOMI UCBOSCL TA0.2	SPI MISO	
P2.5 - (1) S42 - TB0.4 COM5 - P2.4 - (1) S43 - TB0.3 COM4	SPI CS Display GPIO (!)	
P4.7 +(I) UCBISCI UCBISONI TA1.2 SS		
P2.7 (() (<u>TB0.6</u> ESIC2OUT COM7 S40 P2.6 (() (<u>TB0.5</u> ESIC1OUT COM6 S41	PWM out GPIO (!)	
P3.3 (() (TA1.1) TBOCLK S26 P3.6 (() (TBO.2) UCA1CLK S23	PWM out GPIO (!) PWM out GPIO (!)	
	Timer Capture - GPIO (!)	
P1.3 (1) A3 C3 TA1.2 ESITEST4	GPIO (!)	
P3.1 (i) UCBISDA UCBISIMO S33	GPIO (!)	
PZ.3 HUD UCA0STE H TBOOUTH	GPIO (()	

Microcontroller peripherals - GPIO

- GPIO stands for General Purpose Input/Output pin.
- General-Purpose Input/Output pins are used for simple "on"/"off" communication, such as reading a button or turning on an LED.
- As an input, a GPIO pin tells the microcontroller what voltage is present on the pin (high or low voltage).
- As an output, the microcontroller chooses to set the GPIO pin to output either a high or low voltage.



Microcontroller peripherals - GPIO

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MSP

- As an input, a GPIO pin tells the microcontroller what voltage is present on the pin (high or low voltage).
- As an output, the microcontroller chooses to set the GPIO pin to output either a high or low voltage.

	MSP-EXP430FR6989 Pin map	BoosterPack sta	ndard
	GND		GND
	P2.1 (!) TB0.5 DMAEO UCA0SOMI/RXD	(PWM out)	GPIO (!)
	P1.5 (I) TAO.0 SO UCAOCLK UCBOSTE	SPI CS Wireless	GPIO (!)
-EXP430FR6989	•		GPIO**
			RST
	P1.6 HUCBOSIMO HUCBOSCA HTAD.1	SPI MOSI	
	P1.7 1008050MI 008050L 1140.2	SPI CS Direlar	GPIO
	P2.4 (1) S43 TB0.3 COM4	SPICS other	GPIO
	- P4.7 (I) UCBISCL UCBISOMI TA1.2 S5		GPIO (!)
	• <u>P2.7</u> H(!) HTB0.6 ESIC2OUT COM7 S40	PWM out	GPIO (!)
	$- \frac{P2.6}{(1)} + \frac{TB0.5}{(1)} + \frac{ESIC100T}{(200)} + \frac{COM6}{(1)} + \frac{S26}{(1)} + \frac$	PWM out	
	P3.6 (I) TRO 2 UCALCLE S23	PWM out	
	P3.7 H(!) TB0.3 UCAISTE S22	Timer Capture	GPIO
3	P2.2 (1) TBO.4 UCAOCLK RTCCLK	Timer Capture	GPIO (!)
	P1.3 (1) A3 C3 TA1.2 ESITEST4		GPIO (!)
	P3.0 (1) UCB1CLK S34		GPIO (!)
	P3.1 H(1) HUCBISDA HUCBISIMO S33		
	PZ.3 F(0) FUCAUSTE TBOOUTH		

Microcontroller peripherals - Timers

- Timing is a crucial part of any embedded system, be it controlling the blinking rate of the LEDs or controlling the sampling rate of the ADCs, or a simple delay on the source code.
- Timers can be used to keep track of time (a timer can be set to "tick" every 1ms for example), and counters can be used to count pulses on an external pin for example.



Microcontroller peripherals - Timers

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Microcontroller peripherals - ADC

- ADCs are used to read an analog voltage and convert it into a digital number which the microprocessor can understand.
- These ADCs are devices that can sense the voltage at a given GPIO pin. It takes an analog voltage and converts it to a digital number.





Microcontroller peripherals - ADC

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	MSP-EXP430FR6989 Pin map	BoosterPack standard
MSP-EXP430FR6989	- GND - P2.1 - (()) (TB0.5) DMAE0 UCA0SOMI/RXD - P1.5 - (()) (TA0.0) S0 UCA0CLK UCB0STE - P9.4 - ESICIO - C12 - A12	CND - PWM out - GPIO - (!) - SPI CS wireless - GPIO - (!) - GPIO**
	RST P1.6 UCB0SIMO UCB0SOMI UCB0SCL TA0.1 P1.7 UCB0SOMI UCB0SCL TA0.2 P2.5 (1) S42 TB0.4 COM5 P2.4 (1) S43 TB0.3	SPI MOSI MISO (SPI CS Display) GPIO (!) (SPI CS other) GPIO (!)
	 P4.7	
	P3.6 (1) TB0.2 UCA1CLK S23 P3.7 (1) TB0.3 UCA1STE S22 P2.2 (1) TB0.4 UCA0CLK RTCCLK P1.3 (1) A3 C3 TA1.2 ESITEST4 P3.0 (1) UCB1CLK S34	- (PWM out - GPIO (!) - (Timer Capture - GPIO (!) - (Timer Capture - GPIO (!) - (!)
	P3.1 (!) UCBISDA UCBISIMO S33 (!) UCBISDA UCBISIMO S33 (!) UCA0STE TB0OUTH	

Microcontroller peripherals - UART

- To talk to the external peripherals, some sort of communication protocol is needed. This is taken care of using devices called serial communication controllers.
- One of the earliest communication protocols was UART (Universal Asynchronous Receiver and Transmitter).
- Peripherals are typically separate pieces of circuitry which offload work from the microprocessor.



Microcontroller peripherals – Interrupt controllers

- Interrupt controllers listen to the peripherals for events and reports to the processor once an event occurs.
- Examples of events that can produce interrupts include:
 - GPIO reads 1 or 0
 - Timer countdown reached 0
 - Serial communication received a packet of data
 - ADC conversion has ended.



"Are we there yet?"



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	MOP*EAP450PH0909 Pin map	BOOSTEPPACK Sta	inuaru
	GND		GND
	P2.1 (I) TB0.5 DMAE0 UCA0SOMI/RXD	PWM out	
FR6989	P9.4 ESICIO C12 A12	SPICS WITEJESS	GPIO**
110000	• RST		RST
	P1.6 UCBOSIMO UCBOSDA TAO.1	SPI MOSI	
	P1.7 (UEBOSOMI) UCBOSCL 17A0.2	SPI CS Dimlay	GPIO (!)
	- P2.4 (1) S43 TB0.3 COM4	SPI CS other	-GPIO (!)
	P4.7 (1) UCB1SCL UCB1SOMI TA1.2 S5		(GPIO)((!)
1	P2.7 (!) (TB0.6) ESIC2OUT COM7 S40	(PWM out)	GPIO (!)
	- <u>Р2.6</u> (1) (<u>ТВ0.5</u>) ESIC1OUT (СОМ6) S41-	PWM out	GPIO (!)
	•P3.3 - (1) - TA1.1 + TBOCLK + S26	PWM out	GPIO (!)
(man)	P3.5 - (1) - TB0.2 - UCATCLK - S23	Timer Capture	
	P2.2 (1) TB0.4 UCAOCLK RTCCLK	(Timer Capture)	GPIO (!)
	•P1.3 _(() A3 C3 TA1.2 ESITEST4		-GPIO (!)
	P3.0 (1) UCBICLK S34		
	P2.3 (1) UCA0STE TBOOUTH		GPIO (!)
		1	

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Programming the microcontroller

 An Integrated Development Environment (IDE) for microcontrollers is a software suite that provides a comprehensive set of tools and features to facilitate the development, programming, debugging, and testing of embedded software for microcontroller-based systems.



Programming the microcontroller

• IDEs often come with tools for **programming (flashing)** the microcontroller's memory with the compiled code. This is essential for loading the firmware onto the target microcontroller.





Programming the microcontroller







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Debugging a microcontroller code

 Debugging is the process of identifying, analyzing, and resolving issues within a software or hardware system.



Six Stages of Debugging

- 1. That can't happen.
- That doesn't happen on my machine.
- 3. That shouldn't happen.
- 4. Why does that happen?
- 5.0h, I see.
- 6. How did that ever work?

Debugging a microcontroller code

- Debugging is the process of identifying, analyzing, and resolving issues within a software or hardware system.
- Due to the specialized nature of embedded systems, errors can lead to severe consequences, such as equipment malfunction or even safety hazards.



Six Stages of Debugging

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Debugging a microcontroller code

- Common Debugging Challenges in Embedded Systems:
 - Limited Resources and Processing Power
 - Real-Time Constrains
 - Complex Hardware and Software Interactions
 - Concurrency Issues
 - Unique Platform-Specific Challenges



- The Blinky LED: Using an LED as a microcontroller 'alive' indicator.
- By far the simplest debug tool is a resistor and an LED of your choosing.
- Connected to a spare general-purpose I/O pin (GPIO), it can be used like a latch at a strategic point in the code to leave an electronic breadcrumb.



- The Blinky LED: Using an LED as a microcontroller 'alive' indicator.
- By far the simplest debug tool is a resistor and an LED of your choosing.
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- **Outputting Messages** through serial interfaces (UART) using *printf()*.
- The code behind this function is quite processor intensive.
- Assign different values to be written at different points in your code.

```
Serial.begin(115200);
...
Serial.println("Button pressed...");
...
Serial.println("Value: ");
Serial.write(dataByte);
```

- Instrumentation: place strategic information into an array without / with filtering.
- Observe the contents of the array at a later time.
- The first step when instrumenting a dump is to define a buffer in RAM to save the debugging measurements.



- **Debugging Interfaces:** This opens access to all the internal circuitry, including memory, CPU registers, and all the peripherals.
- While most microcontroller development boards come with an onboard debugger, there are still plenty that don't.





Code example

void setup() {

}

// Open serial communications and wait for port to open: Serial.begin(9600);

while (!Serial) {

; // wait for serial port to connect. Needed for native USB port only

Serial.println("Serial communication initialized.");

```
// initialize digital pin LED_BUILTIN as an output.
Serial.println("Initializing LED_BUILTIN as an output.");
pinMode(LED_BUILTIN, OUTPUT);
Serial.println("Finished setting LED_BUILTIN as an output.");
```

```
// the loop function runs over and over again forever
void loop() {
   Serial.println("LED ON");
   digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the
   voltage level)
   delay(1000); // wait for a second
   Serial.println("LED OFF");
   digitalWrite(LED_BUILTIN, LOW); // turn the LED off by making the
   voltage LOW
   delay(1000); // wait for a second
```



```
Serial communication initialized.

Initializing LED_BUILTIN as an output.

Finished setting LED_BUILTIN as an output.

LED ON

LED OFF

LED ON

LED OFF

LED ON

LED OFF

LED ON

LED OFF

LED ON
```



Some Questions

- Where are global variables and constant values stored in a microcontroller?
- Is *printf()* suitable for debugging in an embedded system?
- Are microprocessors and microcontrollers the same thing?

Thank you for your attention!